# Plasma instabilities

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# Previously...

- Plasma configurations and equilibrium
  - Linear machines, Tokamaks and Stellarators
  - Ideal MHD and the Grad-Shafranov equation
- Collisional transport in toroidal devices
  - Classical transport (small!)
  - Banana orbits and neoclassical transport
- Waves in plasmas
  - Linearisation of ideal MHD equations
  - Propagation of RF waves through plasmas

### **Plasma instabilities**

- Plasmas exhibit a huge range of instabilities
- One of the challenges in fusion research is to find stable plasma configurations
- Understand the limits of performance
- Aim here is to:
  - Show you the basic tools and concepts used to study plasma instabilities
  - Introduce some of the jargon you'll see in papers and conferences
  - Study some common tokamak instabilities

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### Z-pinch

# Start with simplest magnetic confinement configuration: a **Z-pinch**

### Current driven through column of plasma

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### Generates magnetic field.

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## Z-pinch

Generates magnetic field. JxB force compresses plasma

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### **Z-pinch experiments**

MAGPIE at Imperial College (UK)





Z-machine firing at Sandia National Laboratory (USA)

Current of several mega-Amps for a few hundred nanoseconds

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### X-ray observations



m = 0 "Sausage" instability m = 1 "Kink" instability Schlieren photographs from MAGPIE: F.N.Beg *et.al.* PPCF **46** (2004) 1-10

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### Kink instabilities in space plasmas

Coronal loops show signs of being unstable to kink instabilities —►





T.Torok and B.Kliem 2004

Laboratory plasma jets

S.C.Hsu and P.M.Bellan PoP 12, 032103 (2005)

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## **Plasma modelling**

Many different plasma models to choose from:



### Plasma modelling

#### Another set of models based on averaging over gyro-orbits



### Plasma modelling

### Models classified into "Kinetic" and "fluid"



- Ideal MHD makes several assumptions:
  - Length-scales >> Larmor radius
  - Length-scales >> mean free path
  - Time-scales >> Cyclotron, collision times



- Ideal MHD makes several assumptions:
  - Length-scales >> Larmor radius
  - Length-scales >> mean free path
  - Time-scales >> Cyclotron, collision times
- Assumes plasma is locally close to thermal equilibrium (i.e. Maxwellian distribution), which requires collisions
- Collisions cause dissipation (e.g. Resistivity, viscosity), which are not included in ideal MHD

If ideal MHD makes so many assumptions, why use it?

• Ideal MHD equations include the essential physics of plasma instabilities in a (relatively) simple set of equations:

$$\begin{aligned} \frac{\partial n}{\partial t} + \nabla \cdot (n\mathbf{v}) &= 0 & \text{Density} \\ n \left[ \frac{\partial \mathbf{v}}{\partial t} + \mathbf{v} \cdot \nabla \mathbf{v} \right] &= \mathbf{J} \times \mathbf{B} - \nabla P & \text{Momentum} \\ \frac{\partial P}{\partial t} + \mathbf{v} \cdot \nabla P &= -\gamma P \nabla \cdot \mathbf{v} & \text{Pressure} \\ \frac{\partial B}{\partial t} &= \nabla \times (\mathbf{v} \times \mathbf{B}) & \text{Magnetic field} \end{aligned}$$

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- Additional (non-ideal) effects tend to allow new types of instability. Resistivity in particular allows field-lines to reconnect, however:
- Instabilities described by ideal MHD ("ideal" instabilities) tend to be the fastest and most violent. A plasma which is ideally unstable probably won't last long.

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- Instabilities described by ideal MHD ("ideal" instabilities) tend to be the fastest and most violent. A plasma which is ideally unstable probably won't last long.
- Many non-ideal instabilities are variations on ideal instabilities, and lots of the jargon is from ideal MHD

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Main reason to use ideal MHD is: It works much better than it "should" do, even in hot (i.e. nearly collisionless) plasmas

 Perpendicular to the B field, movement is restricted and the effective mean-free-path is approximately the gyro-radius
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- Perpendicular to the B field, movement is restricted and the effective mean-free-path is approximately the gyro-radius
   As long as perpendicular length-scales are long compared with the gyro-radius then the fluid approximation is ok
- Parallel to the field,
  - the mean-free-path is very long
  - However, gradients in this direction also tend to be very small.
  - Kinetic modifications to MHD primarily modify parallel dynamics.
  - As we shall see, parallel dynamics are not very important for determining when *linear* instabilities start.

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# Magnetic field curvature and pressure

Ideal MHD momentum equation

$$n\left[\frac{\partial \mathbf{v}}{\partial t} + \mathbf{v} \cdot \nabla \mathbf{v}\right] = \mathbf{J} \times \mathbf{B} - \nabla P$$

JxB term can be written as:

$$\mathbf{J} \times \mathbf{B} = \frac{1}{\mu_0} \left( \nabla \times \mathbf{B} \right) \times \mathbf{B}$$
$$= \frac{1}{\mu_0} \left( \mathbf{B} \cdot \nabla \right) \mathbf{B} - \frac{1}{2\mu_0} \nabla B^2$$

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JxB term can be written as:

Plasma pressure

$$\mathbf{J} \times \mathbf{B} = \frac{1}{\mu_0} (\nabla \times \mathbf{B}) \times \mathbf{B}$$
$$= \frac{1}{\mu_0} (\mathbf{B} \cdot \nabla) \mathbf{B} \left( \frac{1}{2\mu_0} \nabla B^2 \right)$$
Magnetic processor

Magnetic pressure



### Sausage instability



Where plasma gets narrower, B field gets stronger. Squeezes plasma out of narrow region and so enhances the instability

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### Kink instability



Field-lines spread apart

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## Kink instability



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- Same as calculating wave dispersion relations
- Linearise the ideal MHD equations by splitting into equilibrium and a small perturbation:
  - $n = n_0 + \delta n$

$$P = P_0 + \delta P$$

$$\mathbf{v} = \mathbf{v}_0 + \delta \mathbf{v}$$

- $\mathbf{B} = \mathbf{B}_0 + \delta \mathbf{B}$
- Substitute into the equations e.g. Density equation:

$$\frac{\partial}{\partial t} \left( n_0 + \delta n \right) = -\nabla \cdot \left[ \left( n_0 + \delta n \right) \left( \mathbf{v}_0 + \delta \mathbf{v} \right) \right]$$

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$$\frac{\partial}{\partial t} \left( n_0 + \delta n \right) = -\nabla \cdot \left[ \left( n_0 + \delta n \right) \left( \mathbf{v}_0 + \delta \mathbf{v} \right) \right]$$

Expand terms:

$$\frac{\partial n_0}{\partial t} + \frac{\partial \delta n}{\partial t} = - \nabla \cdot (n_0 \mathbf{v}_0) - \nabla \cdot (n_0 \delta \mathbf{v}) - \nabla \cdot (\delta n \mathbf{v}_0) - \nabla \cdot (\delta n \delta \mathbf{v})$$



$$\frac{\partial}{\partial t} \left( n_0 + \delta n \right) = -\nabla \cdot \left[ \left( n_0 + \delta n \right) \left( \mathbf{v}_0 + \delta \mathbf{v} \right) \right]$$

Expand terms:



Remove all terms with only equilibrium terms, or more than one perturbed quantity (nonlinear terms)





Write perturbations of the form:

$$\delta n(r,\theta,z) = \delta n(r) e^{im\theta} e^{-ikz}$$

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Write perturbations of the form:

$$\delta n(r,\theta,z) = \delta n(r) e^{im\theta} e^{-ikz}$$

Need to solve this throughout plasma, then match solutions in the vacuum region outside. Long and messy calculation...

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### Stabilising kink modes

Add a magnetic field along the plasma:



As magnetic field has a pressure (i.e. Energy per unit volume), it takes energy to compress magnetic field-lines



## Stabilising kink modes

Add a magnetic field along the plasma:



#### Kruskal-Shafranov condition

Adding a field along the plasma column (B<sub>z</sub>) stabilises sausage and kink instabilities with wavelengths less than:

 $\frac{2\pi r B_Z}{R}$  $L_s =$ 

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### Tokamaks

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### Tokamaks

Wrap a z-pinch into a torus



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Longest length is  $2\pi R$ 

Need to stabilise all wavelengths shorter than this, so

$$L_{s} > 2\pi R \Rightarrow \frac{2\pi r B_{z}}{B_{\theta}} > 2\pi R \qquad \text{i.e.} \quad \frac{r B_{z}}{R B_{\theta}} > 1$$
Called "Safety  
factor", and in  
general written as: 
$$q = \frac{1}{2\pi} \oint \frac{r B_{z}}{R B_{\theta}} d\theta > 1$$
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### Sawteeth in tokamaks

- What happens when q < 1 in tokamaks?
- Repetitive drops in core temperature and density
- First reported by von Goeler et al 1974
- Clearly seen on soft x-ray signals as a sawtooth pattern



### Sawteeth in tokamaks

• When the plasma current becomes too peaked on axis, the safety factor q can drop below 1 in the core



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### Sawteeth in tokamaks

- When the plasma current becomes too peaked on axis, the safety factor q can drop below 1 in the core
- This is then thought to lead to a kink-type instability NB: Called "internal" kink since the boundary is not affected Contrast with (much more dangerous) "external" kink where the boundary does move
- A reconnection then occurs (non-ideal effects important here)
- The hot core is expelled along with some current, bringing q up again



"Fusion Simulation Project Workshop Report" by Arnold Kritz and David Keyes

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### Summary and key points

- Ideal MHD provides a convenient model to study plasma instabilities. Works surprisingly well for linear problems, but should always keep in mind the assumptions made
- Z-pinch plasmas are susceptible to sausage (m = 0) and kink (m = 1) instabilities.
- Bending or compressing field-lines takes energy, and magnetic fields behave as if they have a pressure.
- Too much current in the core of a tokamak produces a "Sawtooth" instability when the "safety factor" q drops below 1

Next time: Pressure driven instabilities...

