

# Encoding Quantified CSPs as Quantified Boolean Formulae

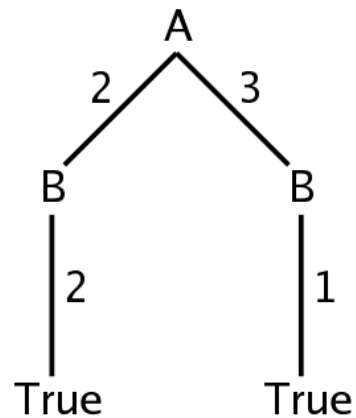
Ian P. Gent, Peter Nightingale and Andrew Rowley

## Finite domain constraint satisfaction problem (CSP)

- Variables with a finite domain
  - e.g.  $A \in \{2, 3\}, B \in \{1, 2, 4\}$
- Constraints placed on variables
  - $A \neq B, A + B = 4$
- A solution is a valid assignment to all variables
  - $A = 3, B = 1$
- NP-complete decision problem

## Introducing quantifiers (QCSP)

- Existential ( $\exists$ ) and universal ( $\forall$ ) quantifiers
- $A \in \{2, 3\}, B \in \{1, 2, 4\}, \exists A \exists B, A \neq B, A + B = 4$
- $\forall A \exists B, A + B = 4$ 
  - Solution tree (strategy)



## Introducing quantifiers (QCSP)

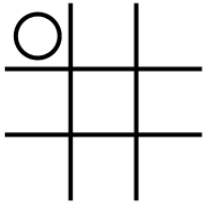
- Quantification order is significant
  - $\forall A \exists B, A + B = 4$
  - $\exists B \forall A, A + B = 4$
- PSPACE-complete decision problem
  - PSPACE algorithm traverses solution tree
- Exponential space to provide a solution

## The game of QCSP

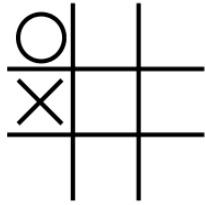
- QCSP can be thought of as a game
- Players are existential and universal
- Some games map into QCSP
  - Connect-4 (Gent and Rowley)
  - A variant of Go (Lichtenstein and Sipser)
  - Othello (Iwata and Kasai)

# Noughts and crosses

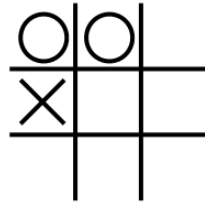
There exists a  
move that  
noughts can make...



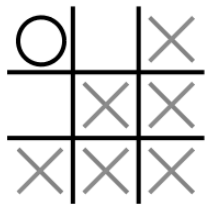
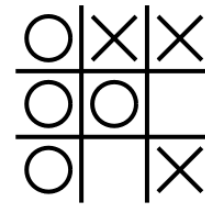
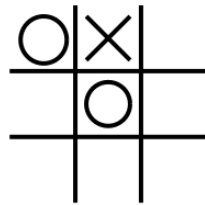
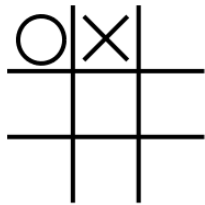
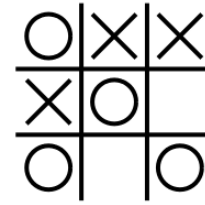
Such that for  
all moves crosses  
can make...



There exists a  
second move  
noughts can make...



Such that eventually  
noughts can win.



## Why consider QCSP?

- Natural generalization of CSP
- Problem solving with uncertainty
  - Uncertain data at solution time e.g. delivery time 10 am $\pm$ 1 hour
    - \* (Minimal) Covering set of solutions (Yorke-Smith and Gervet)
  - Uncertainty resolved during execution of plan
    - \* Game against the environment

## Quantified Boolean Formulae (QBF)

- Subset of QCSP (also PSPACE-complete)
- We consider conjunctive normal form QBF in prenex form

$$\forall a, b \exists c, (a \vee \neg c) \wedge (\neg a \vee \neg b \vee \neg c)$$

- Unit propagation rules similar to SAT — slightly stronger



Why encode?

- QBF is the subject of recent research
  - Basic complete algorithm based on Davis Putnam Logemann Loveland algorithm
  - Conflict and solution directed backjumping (Guinchiglia, Narizzano and Tacchella)
  - Efficient watched data structures (Gent, Guinchiglia, Narizzano, Rowley and Tacchella)
- Take advantage of fast QBF solvers for QCSP

## Direct encoding

- We consider binary QCSP for this work
- Encode CSP variable  $v$  with SAT variables  $x_i^v$  for each value  $i$
- At-least-one clause  $(\bigvee_{i=1}^d x_i^v)$  ( $v$  takes at least one value)
- At-most-one clauses  $\bigwedge_{i=1}^d \bigwedge_{j=i+1}^d (\neg x_i^v \vee \neg x_j^v)$
- Conflict clauses  $(\neg x_i^v \vee \neg x_j^w)$

## Global Acceptability Encoding for QCSP

- Considerably more involved than direct encoding
- *Acceptable* assignment to the encoded QBF corresponds to QCSP assignment
- The formula is required to be *true* for some unacceptable assignments — where universal variables take  $\neq 1$  values
- Additional literal  $z$  in most clauses
- Conflict clauses  $(\neg x_i^v \vee \neg x_j^w \vee z)$
- Prevents unit propagation until innermost universal variable is set

## Local Acceptability Encoding (refinement of above)

- Local  $z_u$  variables are set earlier than  $z$  and allow unit propagation
- $\dots \forall x_i^v \dots \forall x_j^w \dots (\neg x_i^v \vee \neg x_j^w \vee z_w)$
- $\dots \forall x_h^u \dots \exists x_i^v \dots \exists x_j^w \dots (\neg x_i^v \vee \neg x_j^w \vee z_u)$
- Simulates forward checking (Mamoulis and Stergiou)
- Large number of unacceptable assignments

## Adapted Log Encoding (further refinement)

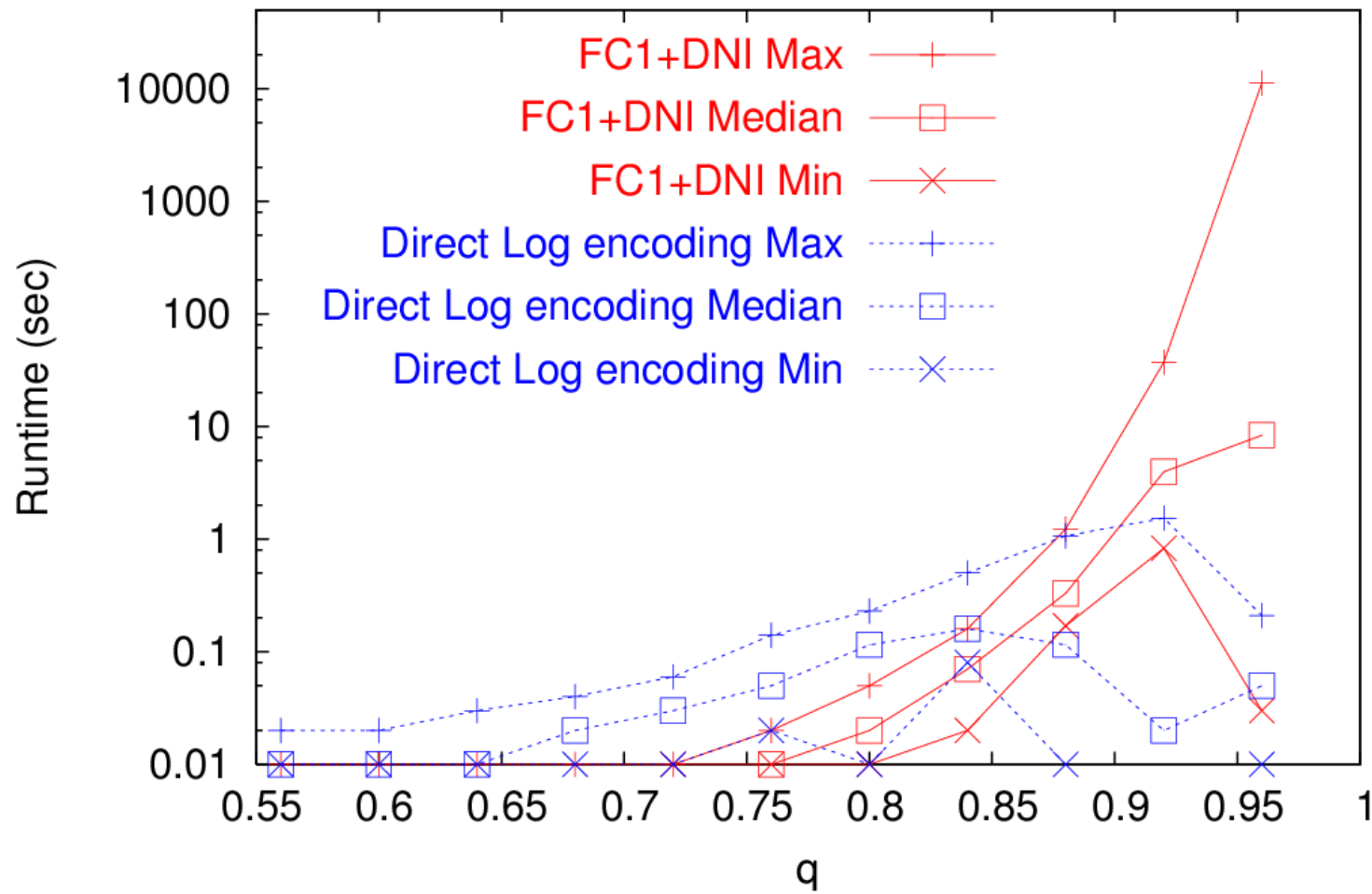
- Unary encoding of universal variables has  $O(2^d)$  unacceptable assignments — Log encoding has  $O(d)$  unacceptable assignments
- Proven correct
- Channel log encoding to unary encoding

$$\begin{aligned} & (z_u \vee x_1^v \vee b_2^v \vee b_1^v \vee b_0^v) \\ & (z_u \vee x_2^v \vee b_2^v \vee b_1^v \vee \neg b_0^v) \\ & (z_u \vee x_3^v \vee b_2^v \vee \neg b_1^v \vee b_0^v) \\ & (z_u \vee x_4^v \vee b_2^v \vee \neg b_1^v \vee \neg b_0^v) \\ & (z_u \vee x_5^v \vee \neg b_2^v \vee b_1^v \vee b_0^v) \end{aligned}$$

- One-way channelling preserves pure literal propagation

# Direct solution vs. encoding

$n = 21, p = 0.5$



## Flaws in QCSPs

- Some instances trivially false
- Universals  $u_1 \dots u_7$  followed by existential  $e$
- Each value of  $e$  conflicts with some value of some  $u_i$
- Artificially shifts phase transition
- Recent work on controlling parameters to avoid this

## Conclusions

- Encoding outperforms direct solution on some problems
  - Sometimes by orders of magnitude
- Low implementation effort
- Support encoding remains open
- Good benchmark problems required



Thank you