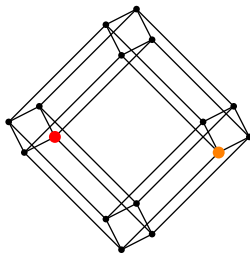


Coupling: co-adapted vs. maximal

(joint work with W.S. Kendall and S. Jacka, University of Warwick)

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Outline

- 1 Introduction
 - Coupling
 - The coupling inequality
- 2 Types of coupling
 - Maximal coupling
 - Co-adapted coupling
- 3 Brownian Motion
- 4 Random walk on the hypercube, \mathbb{Z}_2^n
- 5 Concluding remarks



Coupling

Let X be a Markov process with state space \mathcal{S} . We are interested in the situation where we have two copies of this process, X and Y , started from different states.

Definition

A *coupling* of X and Y is a process (X', Y') on $\mathcal{S} \times \mathcal{S}$, such that

$$X' \stackrel{\mathcal{D}}{=} X \quad \text{and} \quad Y' \stackrel{\mathcal{D}}{=} Y.$$

That is, viewed marginally, X' behaves as a version of X and Y' as a version of Y .

- The *coupling time* is defined by

$$\tau = \inf \{t : X'_s = Y'_s \text{ for all } s \geq t\}$$

- The coupling is *successful* if $\mathbb{P}(\tau < \infty) = 1$
 - τ is not, in general, a stopping time (for the marginal processes nor the joint process)
 - A ‘good’ coupling is usually one with a ‘small’ coupling time τ
- existence of a coupling is trivial: let X' and Y' be independent until they first meet, then stay together
 - this idea goes back to Doeblin (1938)
- a major use of coupling is to provide information about the convergence of $X \dots$

The coupling inequality

Definition

Let μ and ν be probability measures defined on S . The *total variation distance* between μ and ν is given by

$$\|\mu - \nu\|_{TV} = \sup_{A \subset S} (\mu(A) - \nu(A))$$

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Lemma (The coupling inequality)

Let (X, Y) be a coupling as above. Then

$$\|\mathbb{P}(X_t \in \cdot) - \mathbb{P}(Y_t \in \cdot)\|_{TV} \leq \mathbb{P}(\tau > t).$$



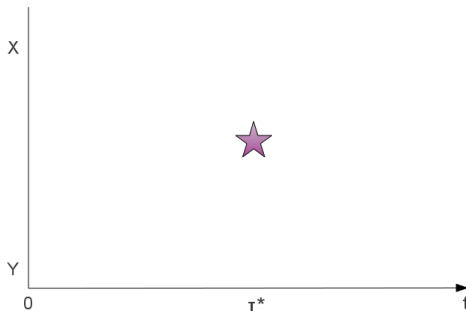
Maximal coupling

It is well known that there exists a **maximal coupling** of X and Y (Griffeath, 1975); that is, a joint process (X^*, Y^*) with coupling time τ^* satisfying

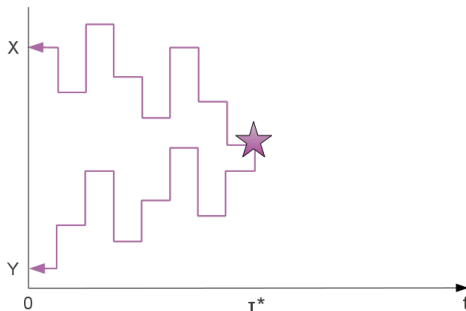
$$\|\mathbb{P}(X_t^* \in \cdot) - \mathbb{P}(Y_t^* \in \cdot)\|_{TV} = \mathbb{P}(\tau^* > t).$$

- Thus there exists a successful coupling for X if and only if X is weakly ergodic

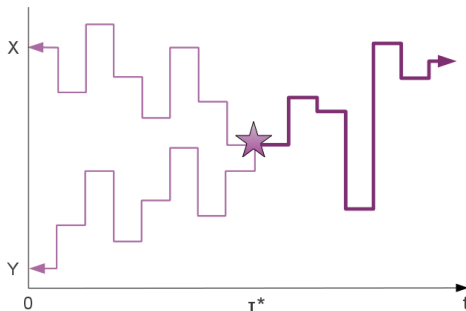
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Co-adapted coupling

Definition

(X, Y) is called *co-adapted* if X and Y are both Markov with respect to a common filtration (\mathcal{F}_t) .

(We don't require that (X, Y) is Markov w.r.t. (\mathcal{F}_t) .)



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- It now suffices to study the first **collision time** of X and Y
 $\rightarrow X$ and Y can be made to agree from this time onwards
- co-adapted couplings are much more intuitive (neither process is allowed to 'cheat' by looking into the future)
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But how good can a co-adapted coupling be?

Brownian motion: a maximal coupling

Consider two Brownian motions, X and Y , on \mathbb{R} , with $X_0 = x$ and $Y_0 = y$ (and $x \geq y$). Write

$$p_t(x, u) = \frac{e^{-(u-x)^2/2t}}{\sqrt{2\pi t}}.$$

It is simple to calculate the total variation distance between these two processes at any time t using the following result...

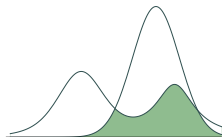
Lemma

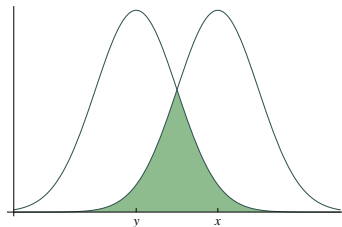
For probability measures μ and ν , let $\mu \wedge \nu$ be their greatest common component, and let λ be a measure that dominates μ and ν . Write

$$f = \frac{d\mu}{d\lambda}, \quad f' = \frac{d\nu}{d\lambda}.$$

Then

$$\|\mu - \nu\|_{TV} = 1 - \int (f \wedge f') d\lambda.$$

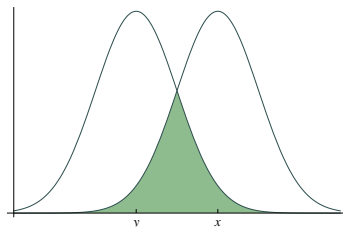




So...

$$\begin{aligned}
 \|\mathcal{L}(X_t) - \mathcal{L}(Y_t)\| &= 1 - 2 \int_{-\infty}^{(x+y)/2} p_t(x, z) dz \\
 &= \text{Erf} \left[\frac{(x-y)/2}{\sqrt{2t}} \right] \\
 &= \mathbb{P}_x \left(\tau_{(x+y)/2} > t \right) .
 \end{aligned}$$

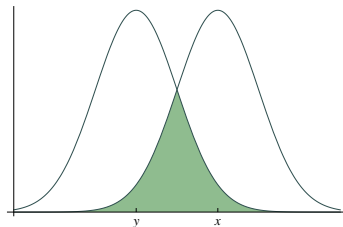
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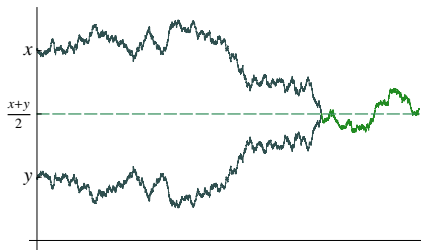
where $\tau_{(x+y)/2} = \inf \{t \geq 0 \mid X_t = (x+y)/2\}$.

Thanks to the symmetry of BM, this shows that *reflection coupling* is maximal for X and Y . In other words, if we define Y by

$$Y_t = \begin{cases} y - (X_t - x) & \text{for } t \leq \tau_{(x+y)/2} \\ X_t & \text{for } t > \tau_{(x+y)/2}, \end{cases}$$

then

$$\|\mathcal{L}(X_t) - \mathcal{L}(Y_t)\| = \mathbb{P}_x(\tau_{(x+y)/2} > t) = \mathbb{P}(X_t \neq Y_t).$$



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Perhaps surprisingly...

Lemma

*Under these initial conditions, reflection coupling for the pair of Brownian motions (X, Y) is **not** maximal*

However, reflection is an *optimal co-adapted* coupling for X and Y when Y_0 is randomised using *any* distribution:

- any co-adapted coupling must be conditioned at time zero upon the σ -algebra $\mathcal{F}_0 = \sigma \{X_s, Y_s : s \leq 0\}$;
- in particular, the coupling scheme at time zero is conditioned on the event $\{Y_0 = y\}$;
- so the best that any co-adapted coupling can do is to match the coupling time of a maximal coupling between X and Y when $(X_0, Y_0) = (x, y)$, averaged over the distribution of Y_0 ;
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Question

Is there an intuitive description of a *maximal* coupling under these initial conditions?

Some extensions

- A similar set of results holds for couplings of two Ornstein-Uhlenbeck processes.
- What about couplings for more general diffusions?

$$dX_t = b(X_t) dt + \sigma(X_t) dB_t$$

Question

Is *reflection* (reflecting B_t) maximal when X_0 and Y_0 are deterministic?

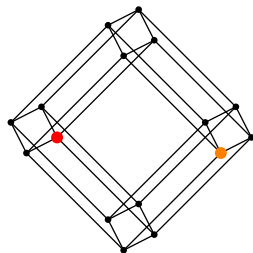
- it seems natural to conjecture that reflection is not maximal when $X_0 = x$ and Y_0 is randomised
- but is reflection still a (unique) optimal co-adapted coupling?

Random walk on the hypercube, \mathbb{Z}_2^n

Let \mathbb{Z}_2^n be the group of binary n -tuples, under coordinate-wise addition modulo 2:

- this is the set of vertices of an n -dimensional cube
- we write $x \in \mathbb{Z}_2^n$ as $x = (x(1), \dots, x(n)) \in \{0, 1\}^n$

This is one of the simplest groups on which to study random walks, due to its high level of symmetry.

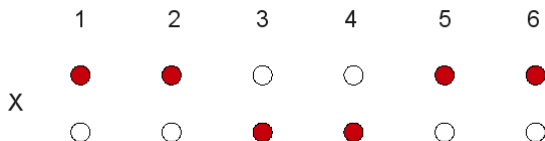




We define a simple, symmetric, continuous-time random walk X on \mathbb{Z}_2^n as follows:

- let Λ_i , $1 \leq i \leq n$, be independent unit-rate Poisson processes
- at incident times of Λ_i , the i^{th} coordinate of X flips to its opposite value (0 or 1)
- unique equilibrium distribution is $\text{Uniform}(\mathbb{Z}_2^n)$

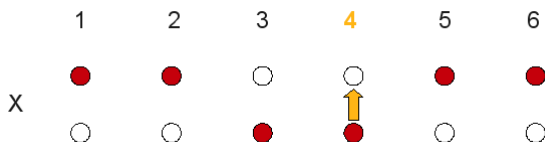
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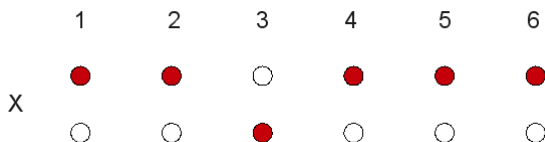
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Now suppose that we wish to couple two such random walks, X and Y , with $X_0 = (0, 0, \dots, 0)$ and $Y_0 \sim \text{Uniform}(\mathbb{Z}_2^n)$

Maximal coupling

An almost-maximal coupling was described by Matthews (1987):

- not co-adapted, but still intuitive!
- expected coupling time $\sim (\log n)/4$

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But how good can a co-adapted coupling be for this process?

Optimal co-adapted coupling

Any co-adapted coupling must satisfy three constraints (all imposed by the marginal processes $X(i)$ being unit-rate Poisson processes):

- in any instant, no. of jumps of (X, Y) cannot exceed two
- all 'single' and 'double' jumps have rates bounded above by 1
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This allows us to describe *any* co-adapted coupling (X, Y) using

- **marked Poisson processes Λ_{ij} ($0 \leq i, j \leq n$)**
- **a $(n + 1) \times (n + 1)$ matrix-valued control process, Q**

Let \mathcal{C} be the class of all co-adapted couplings.

Stochastic control problem

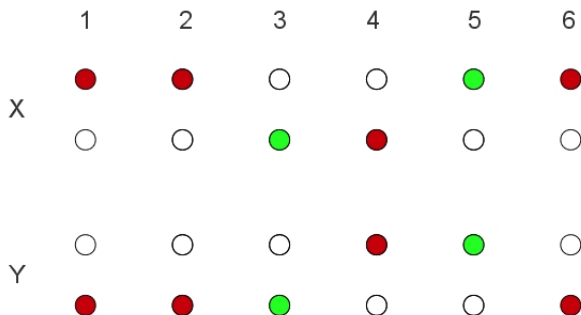
We now just need to find the best control process Q :

Method

- ① Make a **guess** at a good process: call it \hat{Q} ;
- ② Choose a **cost function** v , that measures how good any control process Q is
e.g. $v(Q) = \mathbb{E}[\tau_Q]$, or $v(Q, t) = \mathbb{P}(\tau_Q > t)$;
- ③ Use **Bellman's principle** to show that v is minimized by \hat{Q} .

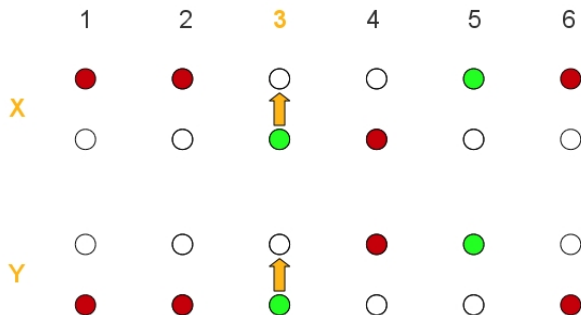
Making a good guess: intuition

- *Matching* coordinates should be made to move *synchronously*:



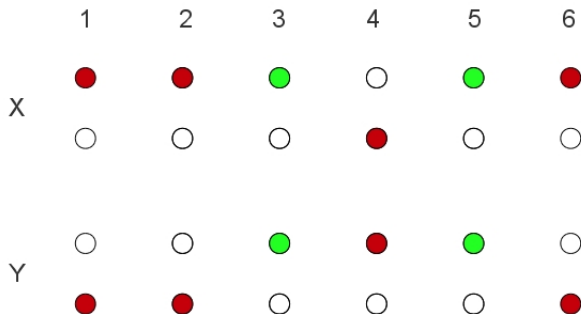
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| | 1 | 2 | 3 | 4 | 5 | 6 |
|---|---|---|---|---|---|---|
| X | | | | | | |
| | | | | | | |
| Y | | | | | | |
| | | | | | | |

- Coupling strategy should depend only on

N_t = no. of unmatched bits at time t

Two possible strategies (I)

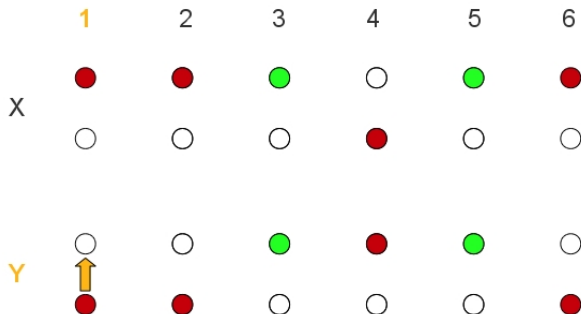
- Allow unmatched bits to evolve **independently**:

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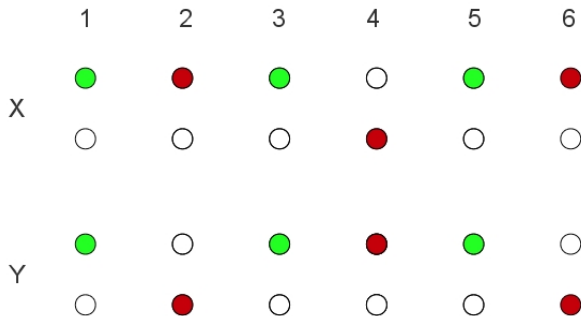
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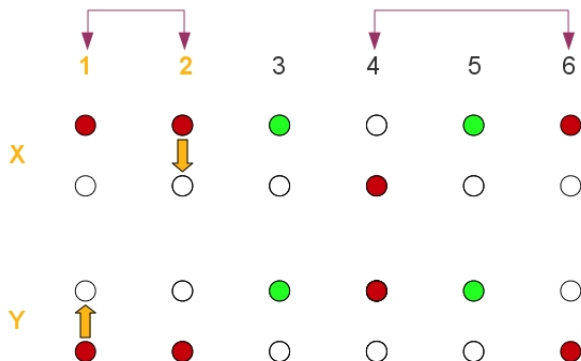
Two possible strategies (II)

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Two possible strategies (II)

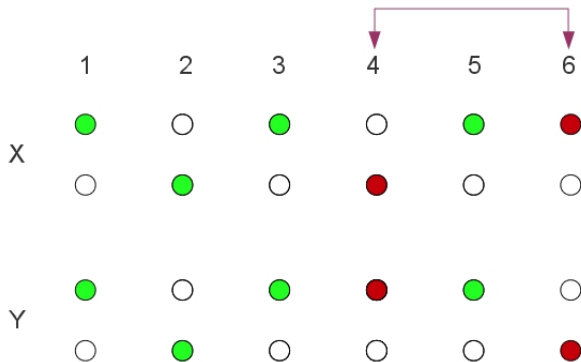
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Main result: the optimal co-adapted coupling

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$$\text{Define } \hat{v}(x, y, t) = \mathbb{P}(\hat{\tau} > t \mid X_0 = x, Y_0 = y) .$$

Main result: the *stochastically* optimal co-adapted coupling

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Define $\hat{v}(x, y, t) = \mathbb{P}(\hat{\tau} > t \mid X_0 = x, Y_0 = y)$.

Theorem (Connor & Jacka, 2008)

For any states $x, y \in \mathbb{Z}_2^n$ and time $t \geq 0$,

$$\hat{v}(x, y, t) = \inf_{c \in \mathcal{C}} \mathbb{P}(\tau^c > t \mid X_0 = x, Y_0 = y) .$$

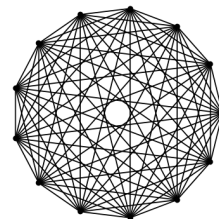
Remarks

- Proof uses notion of *totally monotone functions*;
- The optimal co-adapted coupling is **not** a maximal coupling:

$$\mathbb{E}[\hat{\tau}] \sim \frac{1}{2} \log n \quad \text{but} \quad \mathbb{E}[\tau^*] \sim \frac{1}{4} \log n;$$

- If the rate at which $X(i)$ flips is allowed to *vary* with i then there is, in general, no stochastically optimal coupling.

Analysis can be extended to simple symmetric random walk on G_d^n , where G_d is the *complete graph* on d vertices.



Theorem (Connor, 2009)

There exists a stochastically minimal co-adapted coupling for this random walk:

- *the coupling is not maximal for any fixed d ;*
- *but as $d \rightarrow \infty$, the coupling tends to a maximal coupling.*

Concluding remarks

- For some processes (such as the transposition shuffle on S_n) co-adapted couplings perform *much* worse than maximal couplings, while for others (such as the examples above) there is not a big difference
- Not obvious *a priori* when a co-adapted maximal coupling will exist for a given process, nor how big the 'gap' between maximal and optimal co-adapted couplings will be
- Might lead to an interesting classification system for e.g. random walks on groups
- Possibly interesting consequences for perfect simulation algorithms?

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